

IRF Definitions and Use

• It is conventional to factor the instrument response into effective area, energy dispersion, and point spread function components:

$$R(E', \hat{p}'; E, \hat{p}) = A(E, \hat{p})D(E'; E, \hat{p})P(\hat{p}'; E, \hat{p})$$
(1)

$$= \frac{d\sigma}{dE'd\hat{p}'}(E,\hat{p}) \tag{2}$$

where E is energy, \hat{p} is photon direction, and primed variables indicate measured values and unprimed variables, true values.

- In gtobssim, these IRF components are used as follows:
 - 1. A candidate event, with energy E and direction \hat{p} , is obtained from the flux package, using a cross sectional area A_0 (= 6 m² in Gleam, = max($A(E, \hat{p})$) $\gtrsim 1 \text{ m}^2$ for ST).
 - 2. This event is accepted if $\xi < A(E, \hat{p})/A_0$, where $\xi \stackrel{d}{\sim} [0, 1)$.
 - 3. Apparent energy and direction are then drawn according to the energy dispersion and PSF:

$$E' \stackrel{d}{\sim} D(E'; E, \hat{p})$$
 (3)

$$\hat{p}' \stackrel{d}{\sim} P(\hat{p}'; E, \hat{p})$$
 (4)

• In the likelihood calculation, M, describes the expected distribution of photons,

$$M(E', \hat{p}') = \int dE \, d\hat{p} \, R(E', \hat{p}'; E, \hat{p}) S(E, \hat{p}).$$
(5)

The source model consists of point sources and diffuse emission,

$$S(E,\hat{p}) = \sum_{i} s_i(E)\delta(\hat{p} - \hat{p}_i) + S_G(E,\hat{p}) + S_{\rm eg}(E,\hat{p}).$$
 (6)

The index *i* labels the individual point sources; $s_i(E)$ is the true energy spectrum of source *i*; and \hat{p}_i is its location on the sky. S_G is the Galactic diffuse component, and S_{eg} is the extragalactic diffuse component. Note that the $s_i(E)$ have dimensions of dN/dEdtdA while S_G and S_{eg} have dimensions of $dN/dEdtdAd\Omega$.

Labeling individual photon events with the index j, the logarithm of the Poisson likelihood is

$$\log \mathcal{L} = \sum_{j} \log M(E'_{j}, \hat{p}'_{j}, t_{j}) - N_{\text{pred}},$$
(7)

where the predicted number of photons is

$$N_{\text{pred}} = \int dE' \, d\hat{p}' \, dt \, M(E', \hat{p}', t). \tag{8}$$

DC2 IRF Development Group

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- Use the AllGamma data, $dN/dE \propto E^{-1}$ incident spectrum, sampled uniformly on the upper hemisphere enclosing the LAT.
- Divide the data into bins in log E and cos i space (neglect azimuthal dependence about instrument z-axis).
- Also, divide the work:
 - Final background filters and event class definitions Julie
 - Effective area Jean
 - Energy dispersion Riccardo
 - Point spread function Toby
 - ST implementation JC

See https://confluence.slac.stanford.edu/display/DC2/IRF+Development for the gory details.

Event Class Definitions

• Recall Bill's GoodEvent definitions

```
GoodEvent1 = CTBCORE > 0.10 && CTBBestEnergyProb > 0.30 && CTBGAM > 0.35
GoodEvent3 = CTBCORE > 0.35 && CTBBestEnergyProb > 0.35 && CTBGAM > 0.50
```

• For IRF development and for use by the ScienceTools, it is convenient to partition the data into distinct classes

```
Class A = GoodEvent3
```

These satisfy SRD.

Class B = GoodEvent1 && !GoodEvent3

Include these to maximize effective area while still maintaining reasonably good PSF and energy resolution.

• We partition further by conversion layer,

```
Front = Tkr1FirstLayer > 5.5
Back = Tkr1FirstLayer < 5.5</pre>
```

for a total of four event classes:

0 FrontA 1 BackA 2 FrontB 3 BackB

These numbers are used in gtselect to identify subsets of data based on these classes.

• In addition to Bill's filters, we impose CTBBestZDir < 0.4 to reduce Albedo gammas.





Point Spread Function

• Remove the bulk of the energy-dependence via the scaling function,

$$\tilde{\theta}(E) = \left[(p_1 (E/100)^{-0.8})^2 + p_2^2 \right]^{1/2}$$
(10)

where $(p_1, p_2) = (5.4 \times 10^{-2}, 5.5 \times 10^{-4})$ for front-converting events, and $(p_1, p_2) = (9.6 \times 10^{-3}, 1.3 \times 10^{-3})$ for back-converting events.

• In each log *E*-cos *i* bin, fit the scaled deviation, $\delta \equiv \theta / \tilde{\theta}$, using

$$\frac{1}{N}\frac{dN}{d\delta} = 2\frac{\delta}{\sigma}\left(1 - \frac{1}{\gamma}\right)\left[1 + \frac{1}{2\gamma}\left(\frac{\delta}{\sigma}\right)^2\right]^{-\gamma}$$
(11)

The index γ characterizes the PSF tail at large angular separations. For $\gamma = 2$, we have $\theta_{95}/\theta_{68} = 3$. For $\gamma \to \infty$, this function approaches a Gaussian.

• Smooth behavior across bin boundaries is essential.







$DC2 \ IRFs$

Accessing the IRFs from ROOT

- The ScienceTools interface to the IRFs has been exposed to ROOT: http://glast.stanford.edu/cgi-bin/viewcvs/irfs/rootIrfLoader/
- Example from src/irf_test.C:

```
{
gSystem->Load("rootIrfLoader");
<...snip...>
rootIrfLoader::Aeff aeff_front("DC2::FrontA");
rootIrfLoader::Aeff aeff_back("DC2::BackA");
<...snip...>
for (Int_t i = 0; i < npts; i++) {
    energies[i] = emin*exp(de*i);
    front[i] = aeff_front(energies[i], theta, phi);
    back[i] = aeff_back(energies[i], theta, phi);
}
<...snip...>
}
```

