

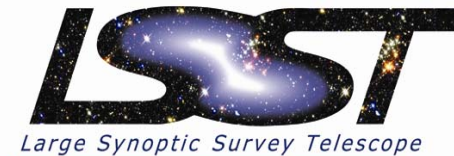
Camera Calibration

D. L. Burke

SLAC

Lead Scientist, LSST Calibrations

SRD Photometric Specifications



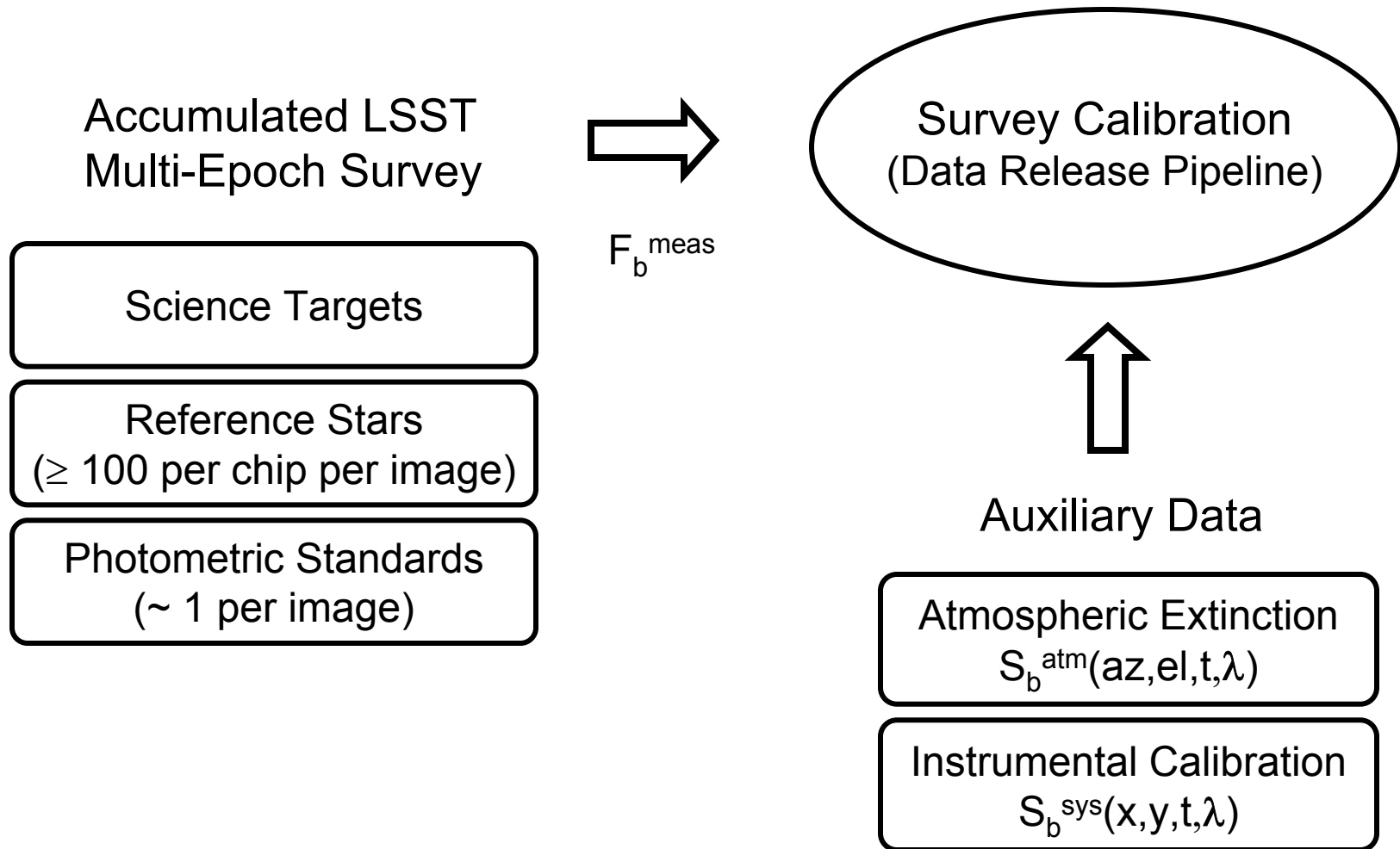
- Repeatability of measured flux over epochs 0.005 mag (rms)
- Internal zero-point uniformity for all stars across the sky 0.010 mag (rms) in g,r,i,z ; 0.020 in other bands
- Transformations between internal photometric bands known to 0.005 mag (rms) in g,r,i,z ; 0.010 to other bands
- Transformation to a physical scale with accuracy of 0.010 mag

LSST specifications are “factor of two” tighter than typically achieved.

E. g. SDSS Sky Server catalogs internal relative calibrations to $\sim 2\%$.

Ivezic, et al. (2004).

Photometric Calibration Elements

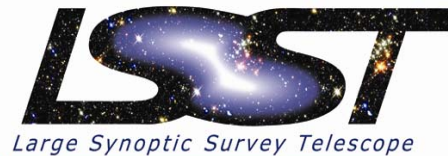


Flow Down of SRD Specifications to Measured Quantities

Design Specification	Repeatability (millimag)	Uniformity (millimag)	Color Accuracy (millimag)
SRD (rms)	5	10	5
Instrumental S_b^{sys}	3	5	3
Atmosphere S_b^{atm}	3	5	3
Image Process F_b^{meas}	3	7	3

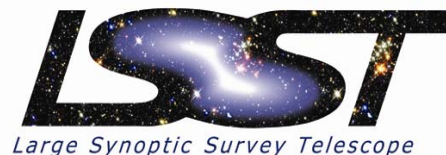
Telescope and Camera

Flowdown to Camera



- Stability – budget is 0.2% for uncontrolled variations in throughput.
 - $(QE(t) \cdot CTE \cdot Gain(t))$ stable to $< 0.2\%$ over times shorter than calibration cadences:
 - Dome screen beginning and end of each night
 - Sky standards every epoch (3-4 days)
- Uniformity – budget is 0.35% for uncontrolled variations in throughput.
 - Relative $(QE(x,y) \cdot CTE \cdot Gain(x,y))$ controlled to $< 0.25\%$.
 - Relative optics/filter transmission $T(x,y)$ controlled to $< 0.25\%$.
 - The product of these two is what really matters.
- Color zero-points – budget is 0.2% for uncontrolled variations.
 - Measure relative $(T(\lambda) \cdot QE(\lambda))$ (over passbands) with error $< 0.2\%$.

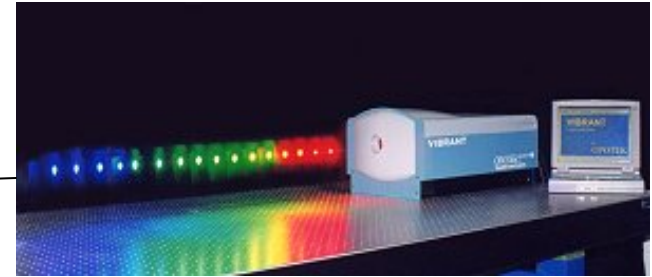
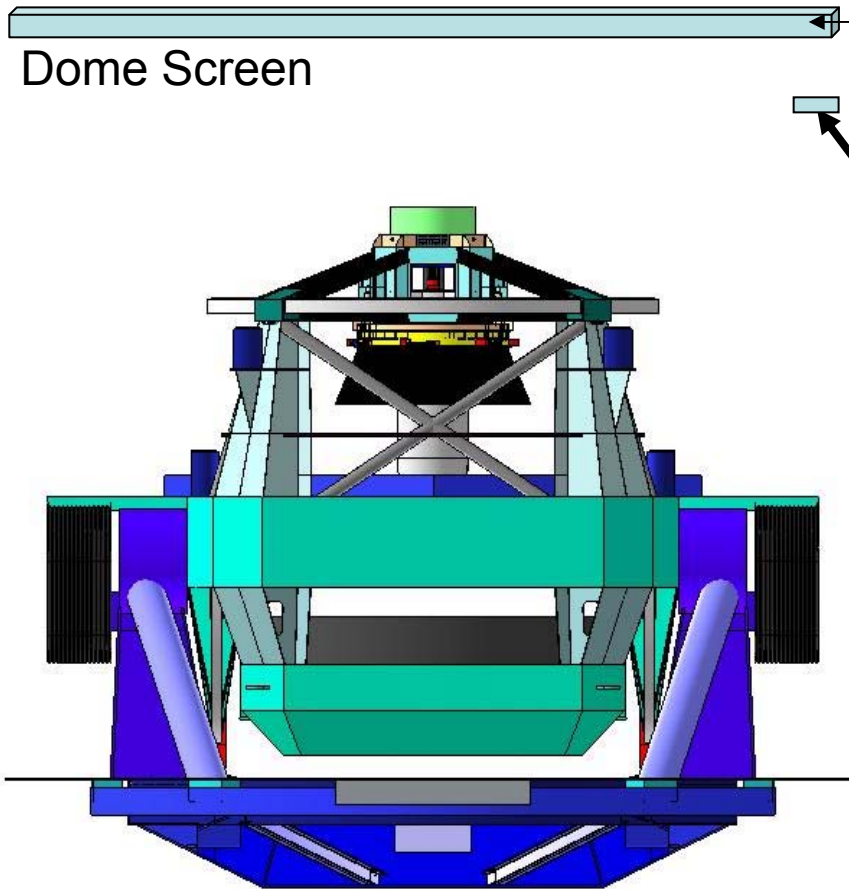
Camera Calibration Matrix



Parameter		Summary Specification	Production Tests	Raft Tests	Camera I&T Calibration	Dome/Sky Calibration
Sensors and Elex						
	QE(λ, x, y)		x	x	x	
	CTE(x, y)		x	x	x	
	Gain(e^-, x, y)	Non-linear < 3% Full Well	x	x		
	Full Well	90000 e-	x	x	x	x
	Cross Talk	residual < 3σ (sky)	s	s	xx	??
	Fringe(λ)	< 5% (p2p)			xx	xx
	Dark Current(x, y)	< 1 e-/s/pix	x	x	xx	xx
	Electronic Noise	< 5 e- rms	x	x	xx	xx
	Persistent Charge	< 0.02% Full Well (20 e-)	s	s	x	x
	Bad Pix Map	<1% bad pix	x	xx	xx	xx
	Thermal Variation			x	xx	
Throughput and Scattered Light						
	Optics/Filters T(λ, x, y)		x			
	T(λ, x, y)·QE(λ, x, y)	0.25% rel meas error			??	
	CTE·Gain(e^-, x, y)	0.25% rel meas error			xx	??
	Throughput (λ, e^-, x, y)	0.35% rel meas error			xx	
	Scattered Light (λ, x, y)	< 3% model error (TPC)			xx	
Key:						
	x	Acceptance value				
	xx	Calibration value				
	s	sample test only				

Instrumental Optical Calibration

Every point on the screen must provide uniform illumination of the angular FOV.



Tunable Laser

Calibrated Photodiode

NIST relative calibration across wavelength (*griz*) to $\sim 10^{-3}$

Issues

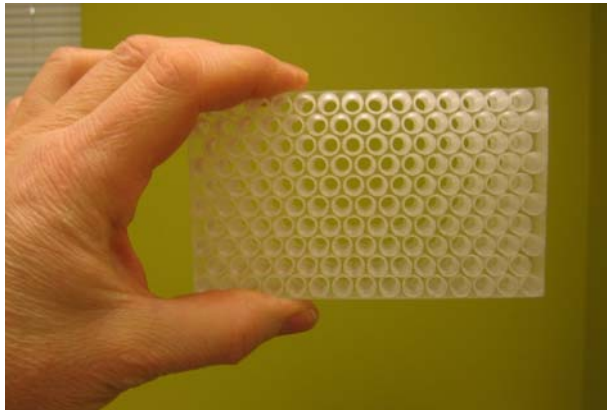
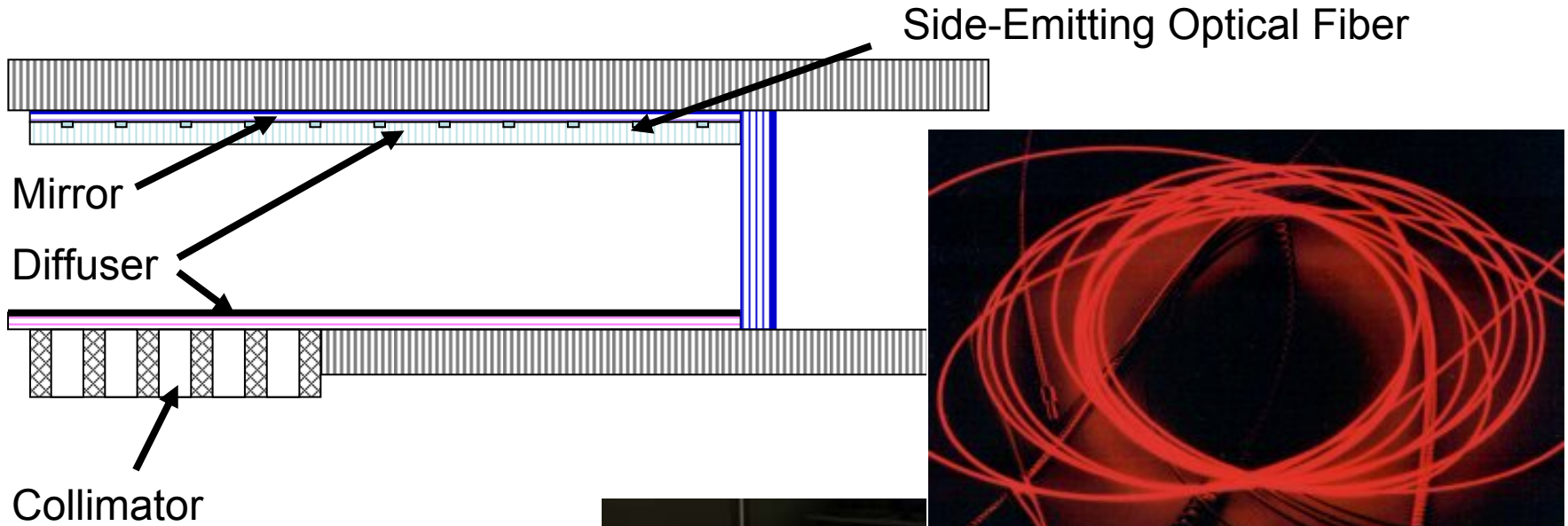
Illumination uniformity
→ Prototype

Stray and scattered light
→ Simulation

Tunable sources below 400nm

Harvard
(Stubbs)

Embedded Fiber Prototype



Purpose: Establish camera photometric performance before integration with telescope.

- Determine fixed operating parameters.
- Determine system response times.
- Determine spatial uniformity and camera “flats”.
- Measure chromatic bandpasses.
- Validate ghosting (scattered light) model.

→ Separate camera and telescope performance.

When ...

Camera is completed and sitting in SLAC assembly room.
Electronics and DAQ working.
Peripherals (shutter, filters, etc) in place and working.

Goal

Verify we are ready to ship the Camera to the mountain.

Method

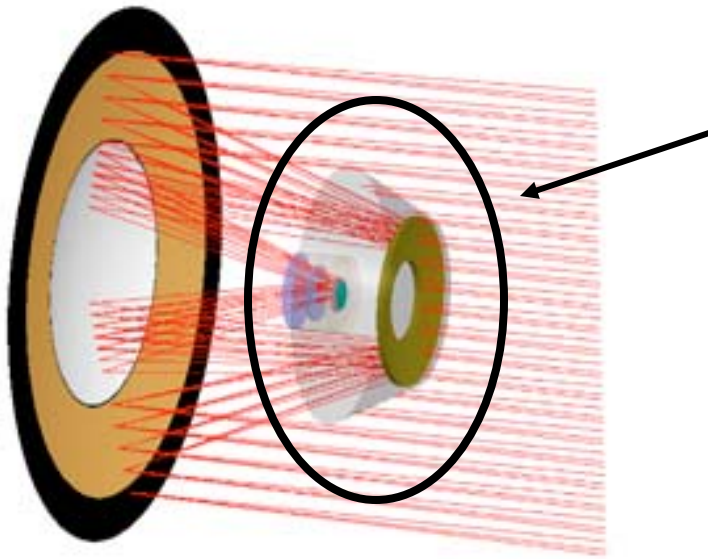
Run the camera as if it were taking data on the telescope!
→ Camera Calibration Optical Bench

Images to Record and Analyze

Bias frames.
Darks (long and short).
Calibration Images



Barrau, et al.



- Consider only the camera
 - Three lenses
 - Filter
 - CCD surface
- LSST non-sequential ZEMAX model

Bechtol, Scacco, and Sonnenfeld

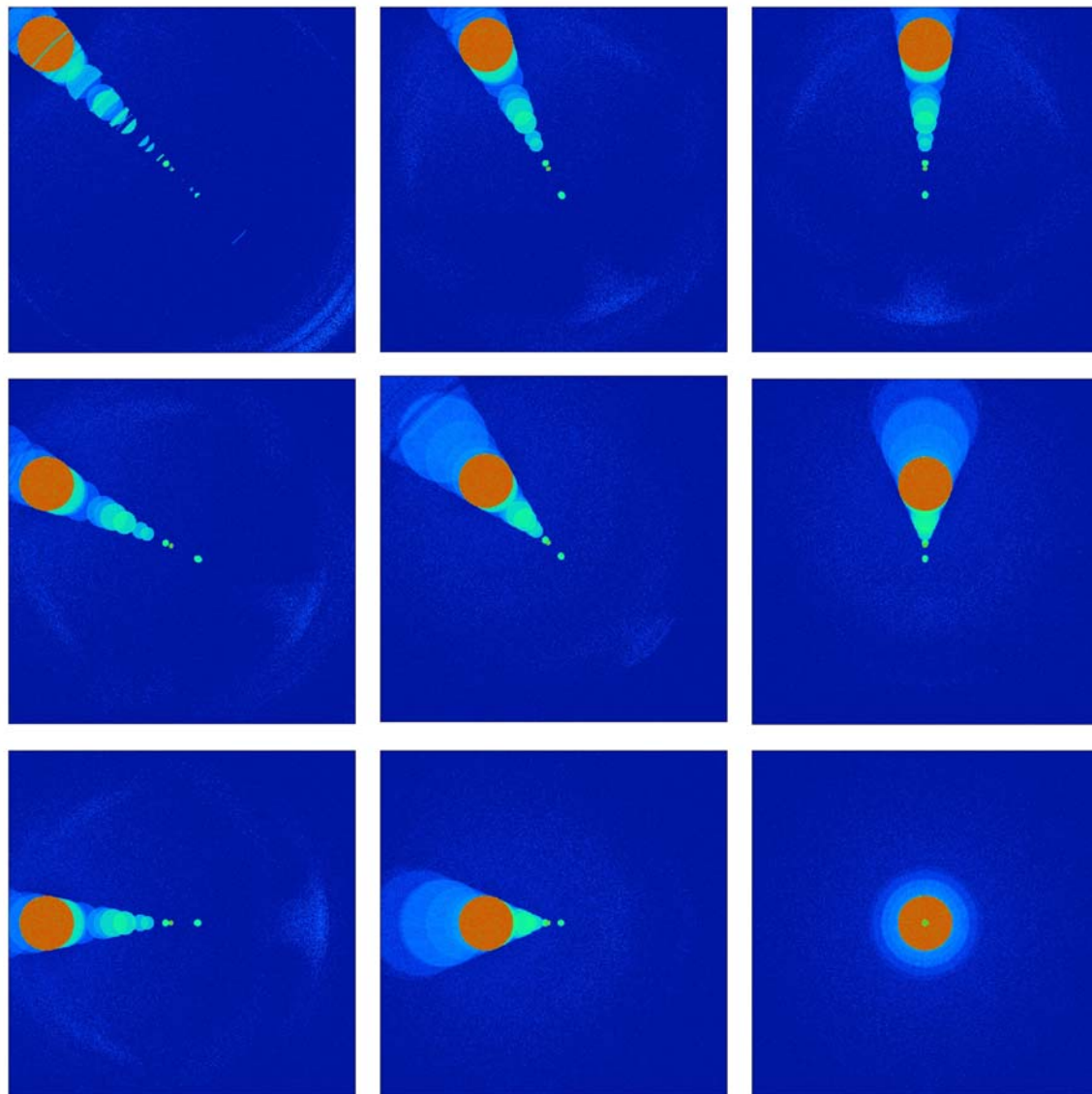
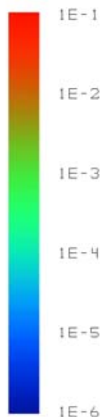
“Headlight” Beam

Center 10 cm diameter beam
over a grid of positions

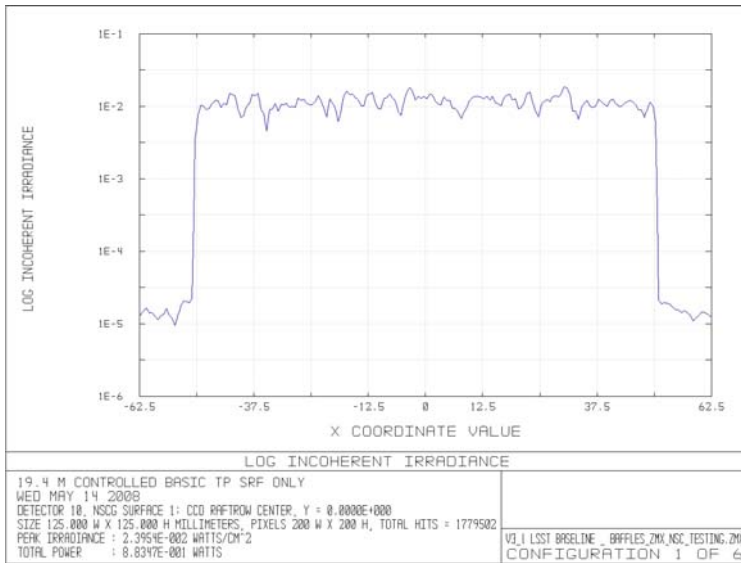
(250,250)	(125,250)	(0,250)
(250,125)	(125,125)	(0,125)
(250,0)	(150,0)	(0,0)

Beam Positions
(cm)

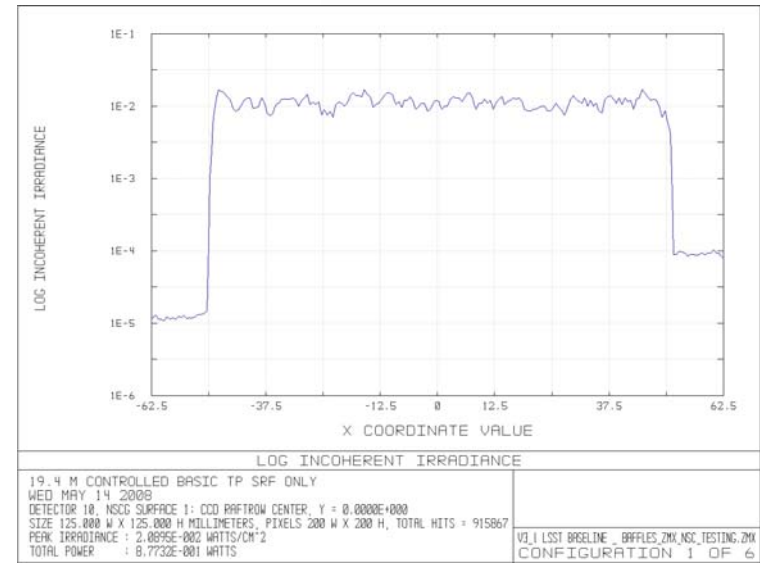
Incoherent irradiance
(W / cm²)



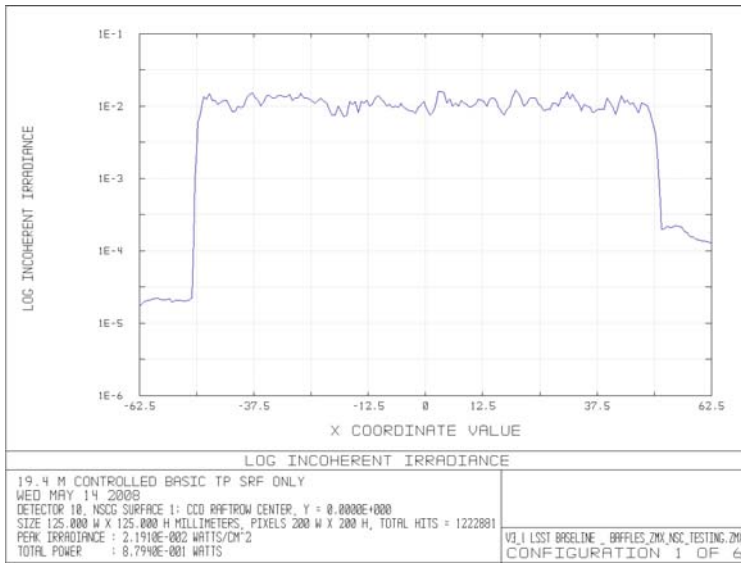
Beam Profiles at Focal Plane



Center (0,0)



Offset 250 cm
(250cm,0)



Offset 125 cm
(125cm,0)

Test beam intensity profiles at focal plane – radial slices

X-Ray Calibration During Camera I&T

Considered implementation of an *in-situ* x-ray system.

Rejected in favor of a temporary “L3” source plate to be used during I&T (and perhaps later at the observatory as needed for recovery after maintenance).

Fixed and shuttered ^{55}Fe sources on the CCD (cold) side of a plate that replaces L3.

Activity and spacing of sources to provide $\sim 10^3$ hits per amplifier readout per 15 sec exposure.

No mechanical design yet.

